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http://speedd-project.eu

**The Architecture Design of the SPEEDD Prototype**

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| **Executive Summary** |

In 1-2 pages give a

- 1-sentence punch line about the contribution of the deliverable

- 1-paragraph presentation of the project goals and the work package goals

- 1-paragraph description of the work presented in the deliverable

- 1-paragraph presentation of how the project (and the state-of-the-art if relevant) benefits from the work.

- 1-paragraph description of the main results/findings of the deliverable

- 1-paragraph presentation of the work to follow, based on the deliverable

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# Introduction

## History of the document

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| --- | --- | --- | --- |
| **Version** | **Date** | **Author** | **Change Description** |
| 0.1 | 1/2/2014 | Alexander Artikis (NCSR) | Set up the document |
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## Purpose and Scope of the Document

Briefly state the purpose and scope of the deliverable, and indicate the target readership

## Relationship with Other Documents

Describe how the deliverable relates to other deliverables and papers

# Main Sections

## System Requirements

This section lays out the main requirements for SPEEDD prototype. The requirements are based on the requirements documents provided by the use cases.

## Approach

The design of the system architecture for a prototype like SPEEDD is an iterative process that starts with the beginning of the project and continuously evolves, as requirements of the different components are better understood and insights are gained. Therefore, a close iterative and collaborative process was carried out between the architecture team in WP6 “Scalability and System Integration” lead by IBM, and the technical teams of the SPEEDD prototype, specifically the teams of the real-time event recognition and forecasting (WP3), real-time decision making (WP4), real-time visual analytics (WP5), scalability (WP6), and the technical teams from the use cases (WP7 and WP8).

To this end we followed the steps below, as illustrated in Figure ‎2.1:

1. Iterative biweekly virtual meetings that included representatives of all partners involved. A very draft architecture presented at M3 of the project has been frequently updated and refined based on input and feedback to the current architecture (described in sections ‎2.3 - ‎2.5).
2. On a case-by-case basis, bilateral virtual meetings with a specific partner to elaborate on a specific issue (e.g., specific API).
3. Face-to-face meetings during the project meetings in May and September 2014.



Figure ‎2.1- SPEEDD design architecture approach

## Conceptual Architecture

This section provides a high-level overview of SPEEDD prototype. The goal is to introduce the main concepts, high-level components and information flow without getting into implementation and technological details.

Figure ‎2.2 illustrates the conceptual architecture of SPEEDD prototype. We separate between the design time and the run time. The products of the design time activities are event processing definitions and decision management algorithms and configurations that will be deployed and executed at the runtime.



Figure ‎2.2 - Conceptual Architecture of SPEEDD Prototype

Historic data used at design time contains raw events reported during the observed period along with annotations provided by domain experts. These annotations mark important situations that have been observed in past and should be detected automatically in future. Visualization tooling is used to sift through historic data to gain insights and create annotations. Domain experts apply tools and methodologies provided by SPEEDD authoring toolkit to extract complex event pattern definitions from the annotated event history. This is a semi-automatic process involving applying machine learning tools to extract initial set of patterns which is further enhanced and translated with help of the domain experts into deployable CEP artefacts.

The runtime part is composed of the CEP component, the automatic decision management component, and visual decision support tooling. SPEEDD runtime receives raw events emitted by the various event sources (e.g. traffic sensors, transactional systems, etc., - depending on the use case) and emits actions that are consumed by the actuators connected to the operational systems or simulators.

The CEP component is capable of detecting and forecasting complex event patterns under uncertainty. It processes raw as well as derived (detected and forecasted) events to detect and forecast higher-level events, or situations. These serve as triggers for the decision management component, which uses domain-specific algorithms to suggest the next best action to resolve or prevent an undesired situation.

The visualization component (further called the dashboard) facilitates decision making process for business users by providing easily comprehensible visualization of detected or forecasted situations along with output of the automatic decision making component – a list of suggested actions to deal with the situation. The SPEEDD system can be run in either open or closed loop mode. In case of the open loop, the user can approve, reject, or modify the action proposed by the automatic decision maker. The closed loop operation does not require user’s approval, - the action is performed automatically[[1]](#footnote-1). A hybrid mode where some types of actions are taken automatically while other types require human attention is also supported; moreover, we believe that this mode is the most realistic one.

## SPEEDD Runtime Architecture

The architecture of the runtime part of SPEEDD follows the “Event-Driven Architecture” paradigm. Every component functions as an event consumer, or an event producer, or a combination of both. The event bus plays a central role in facilitating inter-component communication which is done via events. Figure ‎2.3 provides a refinement of the conceptual architecture described above where the runtime part is represented as a group of loosely-coupled components interacting through events. The event bus serves as the communication and integration platform for SPEEDD runtime.

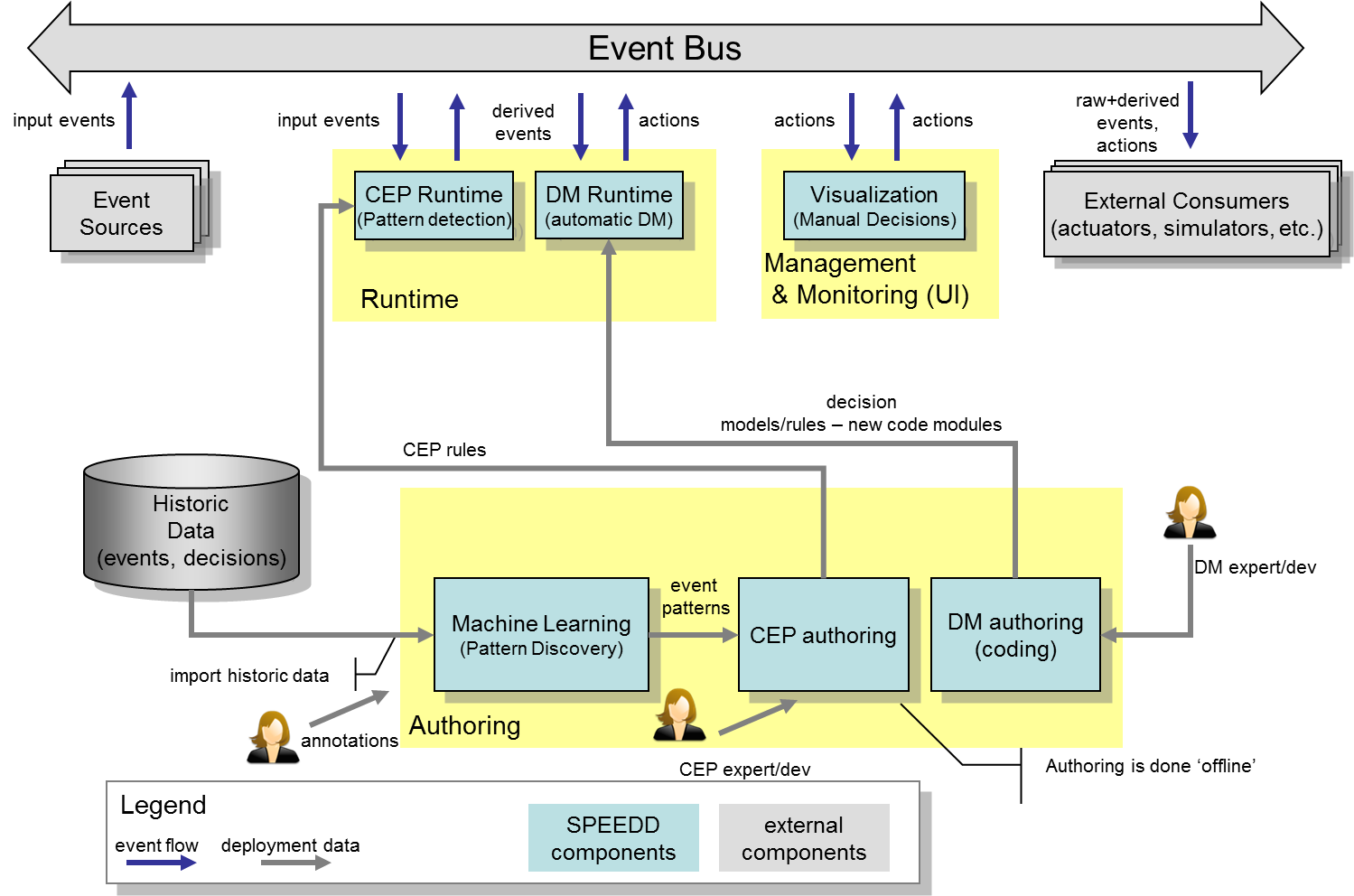


Figure ‎2.3 - SPEEDD - Event-Driven Architecture

Input from the operational systems (traffic sensor readings, credit card transactions) are represented as events and injected into the system by posting a new event message to the event bus. These events are consumed by the CEP runtime. The derived events representing detected or forecasted situations that CEP component outputs are posted to the event bus as well. The decision management module listens on these events so that the decision making procedure is triggered upon a new event representing a situation that requires a decision. The output of the decision making represents the action to be taken to mitigate or resolve the situation. These actions are posted as action events. The visualization component consumes events coming from two sources: the situations (detected as well as forecasted) and the corresponding actions suggested by the automatic decision components. Architecturally there is no difference between these two – both are events that the dashboard is ‘subscribed to’, although having different semantics and presented and handled differently. The user can accept the suggested action as is, modify the suggested action’s parameters, or reject it (and even decide on a different action). In the case where an action to be performed, the resulting action will be sent as a new event to the event bus so that the corresponding actuators are notified.

In the following subsections we are describe the details of the runtime architecture discussing design of each component and explain how the technology is being used to implement it.

Figure ‎2.4 and Figure ‎2.5 illustrate the SPEEDD runtime architecture for the traffic and credit card fraud use cases respectively. These diagrams include the technology platforms used to implement the architecture. We will use these illustrations as we discuss the details of each component.

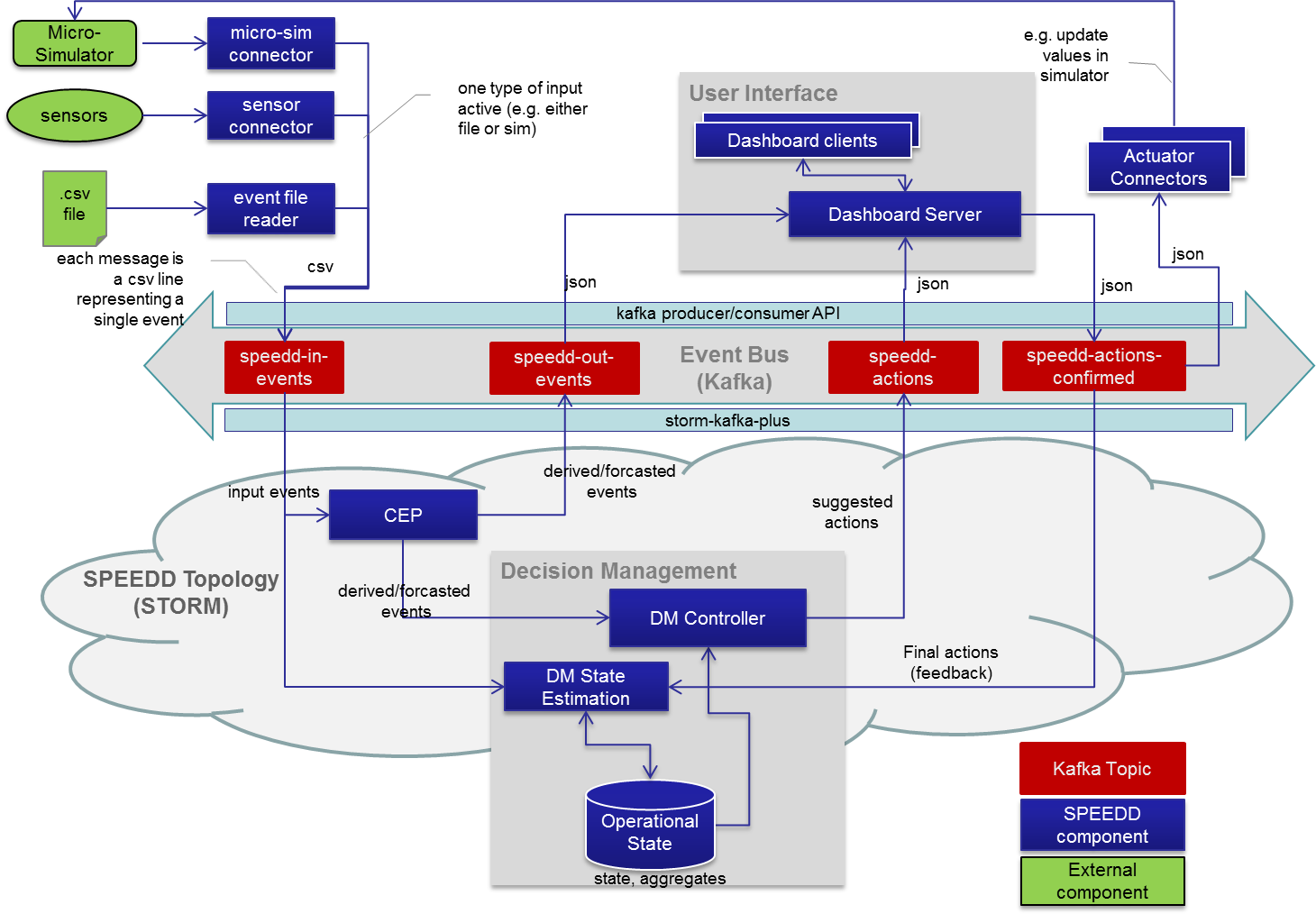


Figure ‎2.4 - SPEEDD Runtime - Event-Driven Architecture (Traffic Use Case)

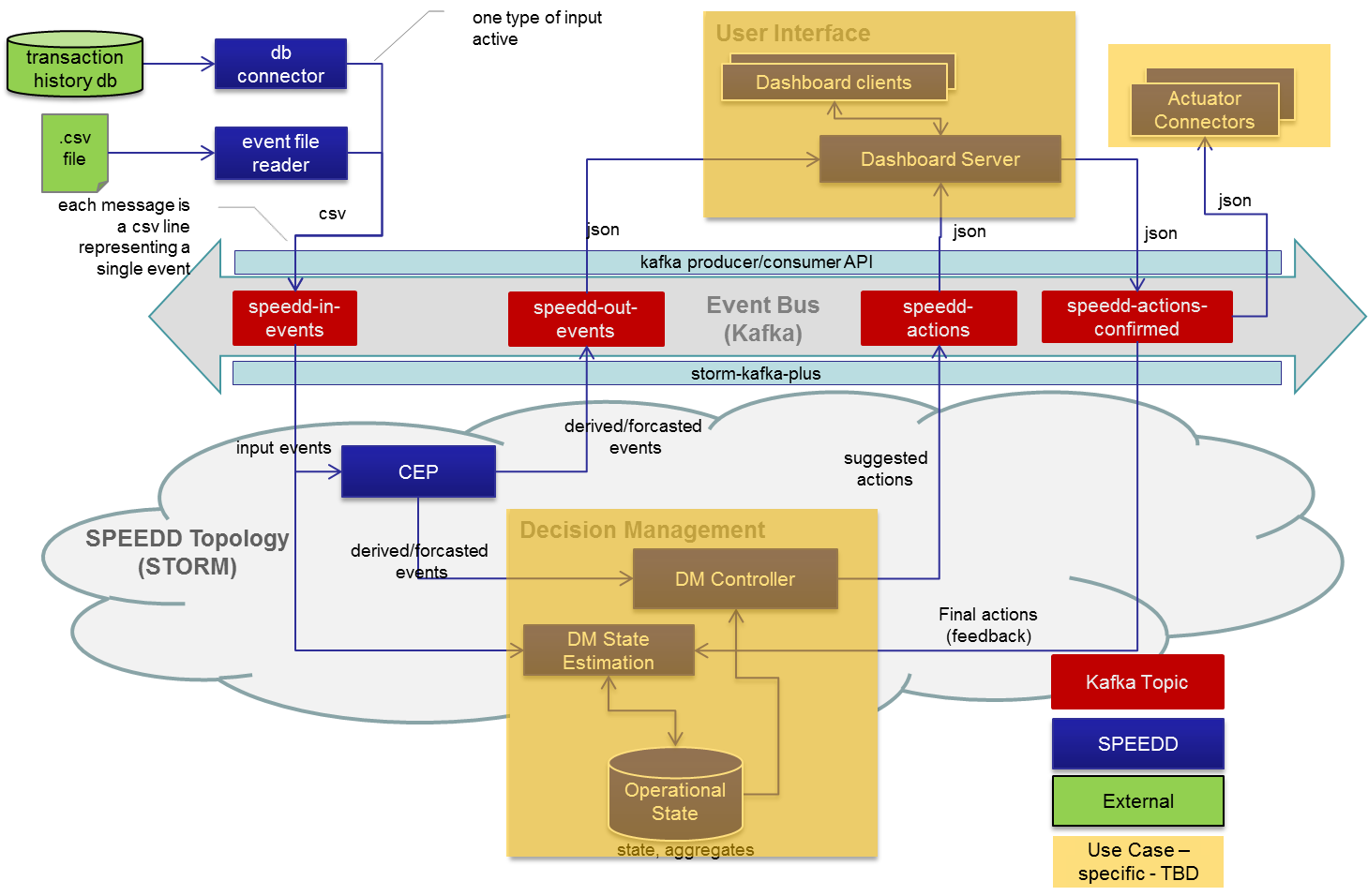


Figure ‎2.5 - SPEEDD Runtime - Event-Driven Architecture (Credit Card Fraud Use Case)

### Event Bus

The technology chosen for the event bus component is Apache Kafka[[2]](#footnote-2). It provides a scalable, performant, and robust messaging platform that matches SPEEDD requirements (see ‎4.5 for our technology evaluation results). To implement routing of the events to event consumers we build upon the topic-based routing mechanism provided by Kafka. In Table ‎2.1 one can find the topics used by SPEEDD runtime along with the information about what components produce events or consume events for every topic.

Table ‎2.1 - Kafka topics in SPEEDD event bus

| Topic Name | Description | Producers | Consumers |
| --- | --- | --- | --- |
| speedd-in-events | Input events | Event sources (e.g. traffic sensor readers, credit card transaction systems, file readers for replay etc.) | CEP runtime |
| speedd-out-events | Detected/Forecasted events | CEP | Decision Management,  Dashboard |
| speedd-actions | Suggested decisions | Decision Management | Dashboard |
| speedd-actions-confirmed | Actions confirmed for execution | Dashboard (in open loop mode), Decision Management (in closed loop mode) | Dashboard, Actuators |

To allow scalable processing of massive stream of messages at high throughput Kafka provides the partitioning mechanism. Every topic can be partitioned into multiple streams that can be processed in parallel, while every partition can be managed on a separate machine. There may be more than one replica for every partition, thus providing resilience in case of failures.

In SPEEDD we exploit Kafka partitioning to build a scalable and fault-tolerant event bus. The topic that receives the biggest incoming traffic is speedd-in-events where all the input events are sent. The decision about the partitioning mechanism to use is use-case specific as we want to achieve nearly uniform distribution of load over different partitions. Below we describe the partitioning approach for each use case, providing the rationale for the design decisions. It is important to mention though that we may change the final partitioning mechanism based on the performance experiments on real and simulated data. We will be able to do that at any stage of the project development, thanks to the highly extensible and customizable partitioning framework that Kafka provides.

#### Partitioning for the Traffic Use Case

Assuming that we get relatively equal amount of events produced by every sensor, we could partition sensor reading events based on the sensor id. This should result in uniform distribution of the messages to partitions, which provides horizontal scalability of the topic.

#### Partitioning for the Credit Card Fraud Use Case

For the credit card fraud use case, the card pan uniquely identifies the card. It is questionable though if we can assume uniform distribution of transactions among all card owners. Therefore the most suitable partitioning seems to be ‘random’ partitioning, that should guarantee uniform partitioning of the messages in the topic.

#### Ordering of events

Kafka guarantees that the order of events submitted to a topic’s partition is preserved within same partition – the consumers will receive them in the same order. However, the order is not guaranteed across partitions. In our case this should not be an issue because the CEP component takes care of the out-of-order events as long as the delay between the event and its preceding event that arrives after that event is not too long – this assumption should be valid with Kafka.

Persistence

Serialization format

Message schema

### Event/Data Providers

Event providers provide the input interface of SPEEDD runtime with the external world. Every event that occurs in the external world that should be taken into account by SPEEDD to detect or predict an important business situation should be sent to the speedd-in-events topic on the event bus (see ‎2.4.1 above) as a message representing the event.

#### Event Providers for Traffic Use Case

As it is illustrated in Figure ‎2.4, events for the traffic use case come from the following sources:

* Traffic sensors – magnetic wireless Sensys sensors buried in the road
* Micro-Simulator – synthetic data generated by the micro-simulator
* Historic data – data from the sensors collected over some period of time that should be replayed to test or demonstrate the SPEEDD prototype

To enable processing of events generated by either of the above sources, a connector should be developed. The connector uses source-specific integration mechanism to read the data from the event sources and send them to SPEEDD event bus using Kafka producer API. The message data model and the format of the serialized representation are described in API and Integration part of this document. We define three connector types corresponding to the types of the event sources:

* Sensor connector[[3]](#footnote-3)
* Micro-sim connector
* File reader connector – replay past events from a file

#### Event Providers for Credit Card Fraud Use Case

The requirements for SPEEDD prototype in regard to the Credit Card Fraud use case only assume running SPEEDD in ‘offline’ mode by replaying historic events . Thus two types of connectors are considered in this design document (as shown in Figure ‎2.5):

* Database connector – replays events from FeedZai transaction database
* File reader connector – replays events from a file (with partially or fully anonymized data)

These connectors reuse the same design framework as described above. For instance, only a small portion of a connector code is use-case specific, where most of the functionality is reused between connectors. In case of the file reader connector the same connector can be used for either use case, while the parsing part is use-case specific.

The data model and the format of the messages are described in in API and Integration part of this document.

### Action Consumption – Actuators/Connectors

The outcomes of SPEEDD are actions that should be applied in the operational environment to resolve a problem or prevent a potential problem. According to the event-driven architecture principles, actions are represented as outbound events and are available to every interested party to receive and process them. The actuators connectors are interface points in SPEEDD architecture responsible for listening on the speedd-actions-confirmed topic for new actions and connect to operational systems to execute respective operations. The following provides details of the actuators for each use case.

#### Actions for the Traffic Use Case

As mentioned above, it is not planned to connect SPEEDD prototype to the traffic operational systems running in production mode. Instead, the detect🡪decide🡪act loop will be implemented and tested using the AIMSUN micro-simulator developed as part of WP8. The traffic actuator connector will listen on the outbound action events (speedd-actions-confirmed topic on the event bus) and execute operations supported by the micro-simulator, e.g. update speed limits, set ramp metering rates, etc. The integration with the event bus for actuators is based on the Kafka consumer API.

#### Actions for the Credit Card Use Case

Per definition of the scope for the SPEEDD prototype, outbound events representing final decisions related to a suspected fraud situation represent the actions – the action information will be written to a log or recorded in a decision data store for further analysis and verification of the prototype functional correctness. No actual operation will be performed. The integration mechanism is the same as for the traffic use case – Kafka consumer API.

### Complex Event Processor

Describe the architecture of PROTON, including implementation on STORM.

### Decision Management

Architecture of the decision management component(s), approaches, issues, etc. Possibly discuss separately the design for every use case.

### Dashboard application

Describe the architecture of the dashboard application.

## Build-Time Architecture

The conceptual view of the build time architecture for SPEEDD is presented in Figure ‎2.6. The goal of the build time is to provide

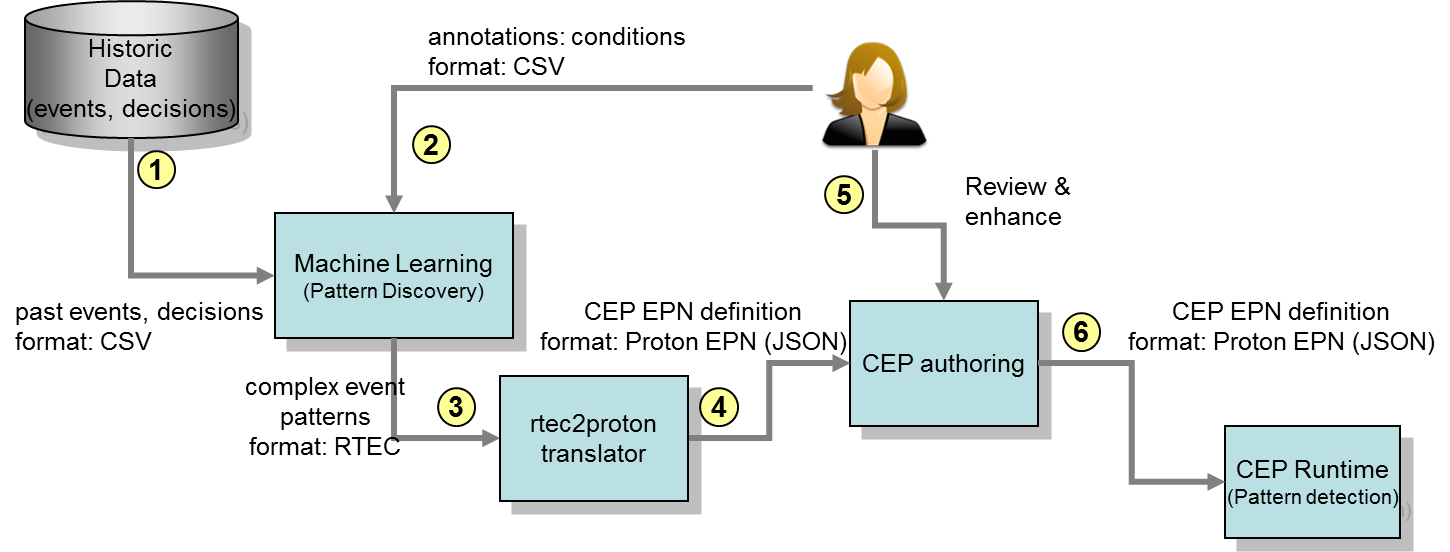


Figure ‎2.6 - SPEEDD Build Time Architecture

### Event Pattern Mining

Describe how machine learning approach is used to extract complex event patterns from annotated historic data.

### Authoring of CEP Rules

Describe the process, challenges, and approach to translation of the CEP patterns discovered in using machine learning into Proton EPN definition.

### Decision Management – the Offline Part

Should see if this is relevant. If it is, describe how decision management component is configured or adjusted based on the exploration of the historic data.

## Integration – APIs and Data Formats

Describe the integration mechanisms between different components and between the system and the outside world. List and describe the APIs and data formats in use.

## Deployment Architecture

TBD – describe proposed deployment architecture

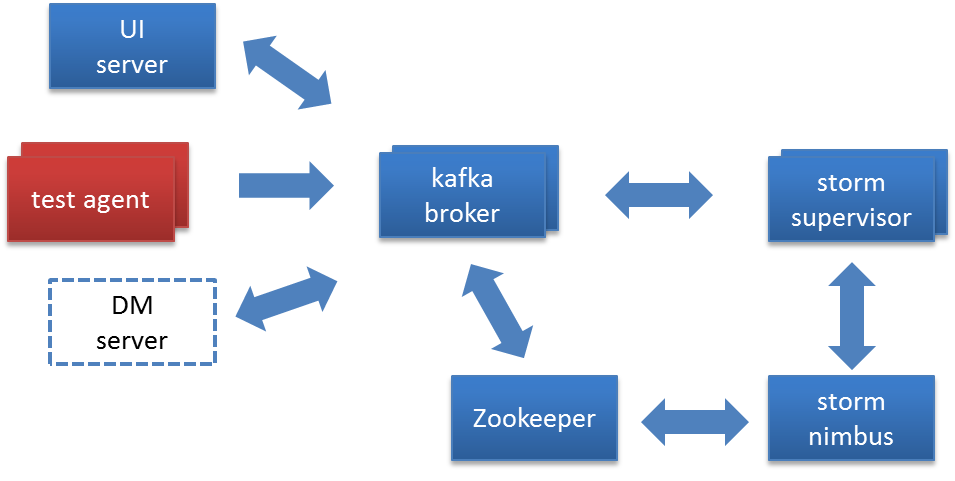


Figure ‎2.7 - Deployment Architecture

## Non-Functional Aspects

### Scalability

Explain why is the proposed architecture is scalable. Describe how the system will scale up and out to match the load.

### Fault Tolerance

Explain what types of failures the system is designed to stand. Describe the designed behavior of the system in case of such failures.

### Testability

Describe the approach to testing the system. Address the functional testing as well as performance testing approach as designed.

# Conclusions

TBD

# Appendix – Technology Evaluation

This could be one or more appendix parts. Here we’ll explain the approach, criteria, and the final choice of the technology stack that was made.

## Stream Processing – requirements and evaluation criteria

## Storm

## Akka

## Spark Streaming

## Choice of the Messaging Platform

1. Actuators are out of scope of SPEEDD prototype. Under automatic action we mean that the message representing the action type and parameters is emitted by SPEEDD, so that the actual operational system listening to action events is supposed to execute it. [↑](#footnote-ref-1)
2. <http://kafka.apache.org/> [↑](#footnote-ref-2)
3. Sensor connector is out of scope for SPEEDD prototype because connecting to the operational systems in production environment is not planned as a goal for the prototype [↑](#footnote-ref-3)